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Journal of Applied Mathematics and Mechanics





V.M. Aleksandrov*, V.Yu. Salamatova

Moscow, Russia

ARTICLE INFO

Article history: Received 20 July 2007

ABSTRACT

The problem of the contact interaction of a cover plate having a base in the form of a narrow rectangle, not resistant to bending deformations but stable to stretching, with an elastic isotropic half-space, loaded at infinity by a stretching force, directed parallel to the boundary of the half-space, is considered. The problem is reduced to an integral equation of the first kind and an approximate method of solving it is indicated. Formulae for the contact shear stress are obtained.

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1. Formulation of the problem

Investigation of the integral equation. We will consider, in a rectangular system of coordinates x, y, z, the elastic half-space $z \le 0$, loaded at infinity with a tension p. The boundary z = 0 is strengthened with a punch having the form of a narrow rectangle of length 2a and width 2ε ($a/\varepsilon \gg 1$) in plan.

The boundary conditions for the elastic half-space have the form

$$\sigma_{zz}(x, y, 0) = 0, \quad \sigma_{zy}(x, y, 0) = 0$$

$$\tau_{zx}(x, y, 0) = \tau(x, y) \quad (|x| \le a, |y| \le \epsilon), \quad \tau_{zx}(x, y, 0) = 0 \quad (|x| > a, |y| > \epsilon)$$

$$u(x, y, 0) = 0 \quad (|x| \le a, |y| \le \epsilon)$$
(1.1)

At infinity

$$\sigma_{xx}(x, y, z) = p \tag{1.2}$$

and the remaining stresses vanish. Here σ_{xx} , σ_{zz} , σ_{zy} , τ_{zx} are the stresses in the half-space, $\tau(x, y)$ is the contact shear between the lower surface of the cover plate and the boundary of the half-space, and u is the displacement of the points of the half-space along the x axis. Using the formula for the displacement, t we reduce problem (1.1), (1.2) to determining the function t(x, y) from the integral equation

$$\int_{-a}^{a} d\xi \int_{-\varepsilon}^{\varepsilon} \tau(\xi, \eta) \left(\frac{2(1-v)}{R} + \frac{2v(\xi-x)^{2}}{R^{3}} \right) d\eta = -\frac{4\pi px}{1+v}; \quad R = \sqrt{(\xi-x)^{2} + \eta^{2}}$$
(1.3)

Here ν is Poisson's ratio of the half-space.

We will use Galin's assumption² that the pressure distribution under the punch in a transverse direction will be the same as is obtained by solving the corresponding plane problem, i.e., we will seek the contact shear stress in the form³

$$\tau(x,y) = \frac{\tau(x)}{\sqrt{\varepsilon^2 - y^2}}, \quad |x| < a, \quad |y| < \varepsilon$$
(1.4)

Prikl. Mat. Mekh. Vol. 72, No. 4, pp. 678-680, 2008.

^{*} Corresponding author.

We substitute expression (2.1) into integral equation (1.3) and use the well-known formulae from Ref. 4 (3.152(4) and 3.158(5)) to represent the integrals in terms of complete elliptic integrals of the first kind $\mathbf{K}(k)$ and the second kind $\mathbf{E}(k)$.

After reduction, integral Eq. (1.3) takes the form

$$\int_{-a}^{a} \tau(\xi) K\left(\frac{\xi - x}{\varepsilon}\right) d\xi = -\frac{\pi p x \varepsilon}{1 + \nu}$$

$$K(t) = \frac{1}{\sqrt{1 + t^2}} \left((1 - \nu) K\left(\frac{1}{\sqrt{1 + t^2}}\right) + \nu E\left(\frac{1}{\sqrt{1 + t^2}}\right)\right)$$
(1.5)

We separate the logarithmic singularity $-(1-\nu)\ln|t|$ in the kernel K(t) and introduce the dimensionless quantities

$$x' = \frac{x}{a}$$
, $\xi' = \frac{\xi}{a}$, $\varepsilon' = \frac{\varepsilon}{a}$, $\varphi(\xi') = \frac{\tau(\xi)}{pa}$

Omitting the primes, we write Eq. (1.5) in the form

$$-\int_{-1}^{1} \varphi(\xi) \ln \frac{|\xi - x|}{\varepsilon} d\xi = -\frac{\pi x \varepsilon}{1 - v^2} - \int_{-1}^{1} \varphi(\xi) F\left(\frac{\xi - x}{\varepsilon}\right) d\xi$$

$$F(t) = \ln|t| + K(t)$$
(1.6)

2. Numerical solution

Eq. (1.6) can be solved using a modified Multhopp-Kalandia method,⁵ which is basically as follows. The solution of Eq. (1.6) can be represented in the form⁶

$$\varphi(x) = \Phi(x) / \sqrt{1 - x^2}$$
 (2.1)

where the function $\Phi(x)$ is at least continuous. Further, at the nodes

$$x_n = \cos \theta_n; \quad \theta_n = \frac{\pi(n-1/2)}{N}, \quad n = 1, 2, ..., N$$
 (2.2)

a Lagrange interpolational polynomial is constructed for $\Phi(x)$, which, in the special case of odd N(N=2i+1) considered here, has the form (the fact that $\Phi(x)$ is an odd function is taken into account)

$$\tilde{\Phi}(\theta) \approx \frac{4}{2i+1} \sum_{n=1}^{i} \tilde{\Phi}(\theta_n) \sum_{m=1}^{i} \cos(2m-1)\theta_n \cos(2m-1)\theta$$

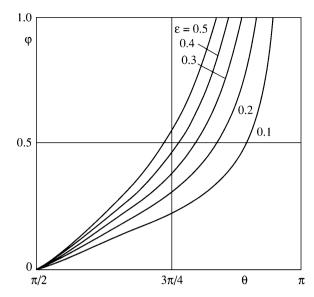
$$0 \le \theta \le \pi, \quad \tilde{\Phi}(\theta) = \Phi(\cos\theta)$$
(2.3)

Substituting expression (2.3) into Eq. (1.6) and using the collocation method we arrive at the following system of algebraic equations for determining the quantities $\tilde{\Phi}(\theta_n)(n=1,2,\ldots,i)$:

$$\sum_{n=1}^{i} \tilde{\Phi}(\theta_{n}) \left(\Psi_{i}^{-}(\theta_{n}, \theta_{k}) + \frac{1}{2} \left[F\left(\frac{\cos \theta_{n} - \cos \theta_{k}}{\varepsilon} \right) - F\left(\frac{\cos \theta_{n} + \cos \theta_{k}}{\varepsilon} \right) \right] \right) =$$

$$= \left(i + \frac{1}{2} \right) \tilde{g}(\theta_{k}), \quad k = 1, ..., i$$

$$\Psi_{i}^{-}(\theta_{n}, \theta_{k}) = \sum_{m=1}^{i} \frac{\cos(2m-1)\theta_{n}\cos(2m-1)\theta_{k}}{m-1/2}, \quad \tilde{g}(\theta_{k}) = -\frac{\varepsilon}{1 - v^{2}} \cos \theta_{k}$$
(2.4)



Numerical results for ν = 0.3 and different values of ε for the contact shear stress are shown in the figure $(\phi(\theta) = -\phi(\pi - \theta))$.

Acknowledgements

This research was financed by the Russian Foundation for Basic Research (08-01-00003, 06-01-00022, 06-08-01595, 07-08-00730).

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Translated by R.C.G.